

Solar Tracker

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Carnegie Mellon Solar Racing



We design, build, and race solar powered boats to practice engineering and to promote clean energy sources.



Purpose of Solar Tracker

- At competition, we charge our batteries in between races with our solar panels
- **Status quo:**
 - Tedious process
 - Inefficient (15%-30%)
 - Manual



Project Description

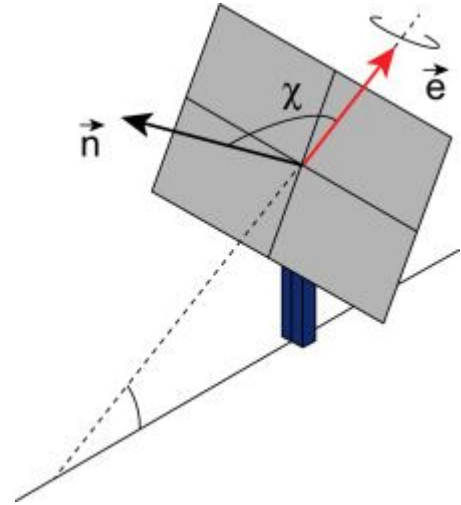
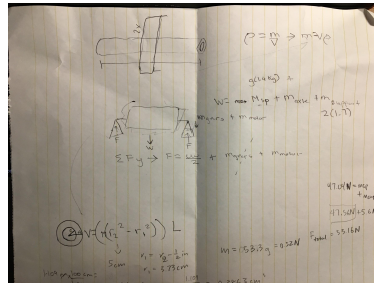
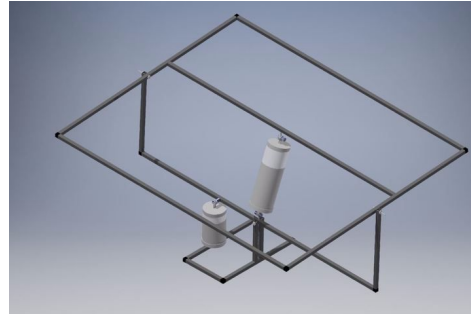
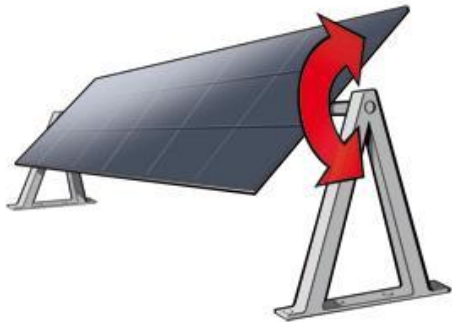
- Goal: Design & build a Solar tracker that
 - Maximizes charging efficiency
 - Automated
 - Portable & light
 - Can hold 2-4 large solar panels
 - Inexpensive

Challenges

- Minimal familiarity with circuitry and EE
- First lead role on a project
- Have to guide 8 freshman engineers through the entire process

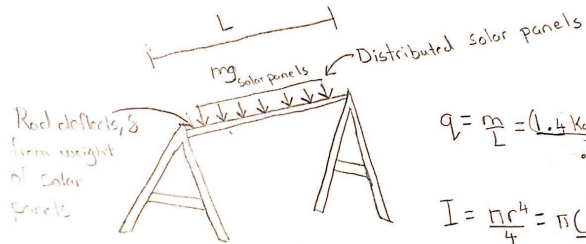
Brainstorming

- Dual axis or 1 axis?
- Power supply
- Support structure
- How do you track the sun?



Hand Calculations & Assumptions

- Deflection of rod ~ 0.2 in



$$q = \frac{m}{L} = \frac{(1.4 \text{ kg} \cdot 9.8 \text{ m/s}^2)}{0.546 \text{ m}} = \frac{25.15 \text{ N}}{\text{m}}$$

$$I = \frac{\pi r^4}{4} = \pi \left(\frac{(.25 \text{ in})}{4} \right)^4 = 1.27 \times 10^{-9}$$

$$\delta_{\text{max}} = \frac{5qL}{384EI}$$

$$\delta_{\text{max, PVC}} = .017 \text{ m} = 3.818 \text{ in}$$

$$E = 2.968 \text{ GPa}$$

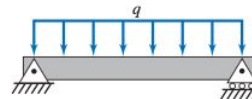
$$\delta_{\text{max, aluminum}} = .004 \text{ m} = .157 \text{ in}$$

$$E = 69 \text{ GPa}$$

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CamScanner



G-2.6



$$v = -\frac{qx}{24EI}(L^3 - 2Lx^2 + x^3)$$

$$v' = -\frac{q}{24EI}(L^3 - 6Lx^2 - 4x^3)$$

$$\delta_C = \delta_{\text{max}} = \frac{5qL^4}{384EI} \quad \theta_A = \theta_B = \frac{qL^3}{24EI}$$

Calculations & Assumptions

- Overall Moment of inertia $\sim .0.282 \text{ kg} \cdot \text{m}^2$

Side View

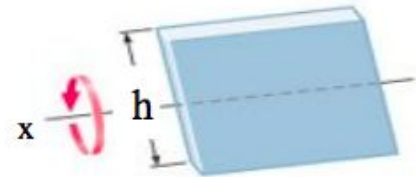
Approximate solar panel as thin rod spinning on an axis

Total Moment of Inertia: $I_{\text{axle}} + 2I_{\text{solar panels}}$

$\frac{1}{2} m_{\text{axle}} r^2 + 2 \left(\frac{m_{\text{solar panel}} h^2}{12} \right)$

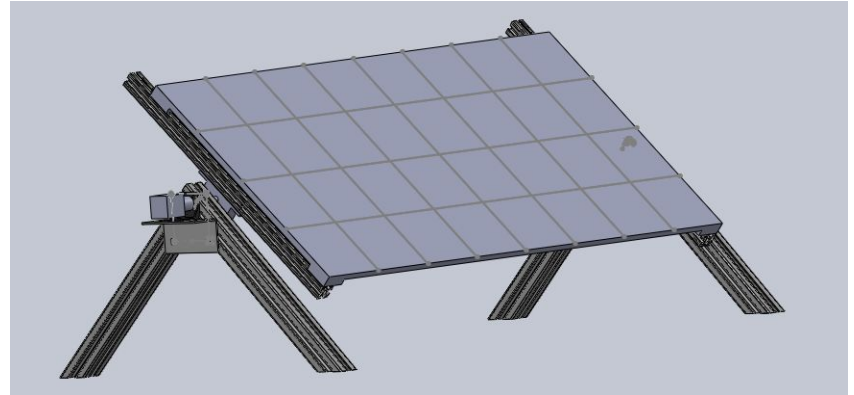
$= 0.282 \text{ kg m}^2 \rightarrow \text{Motor of 1 Nm should do}$

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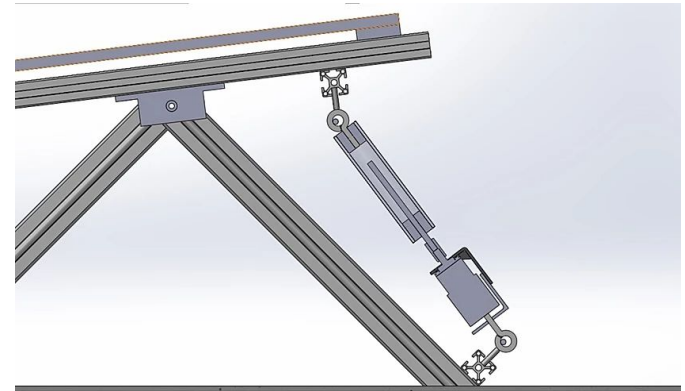
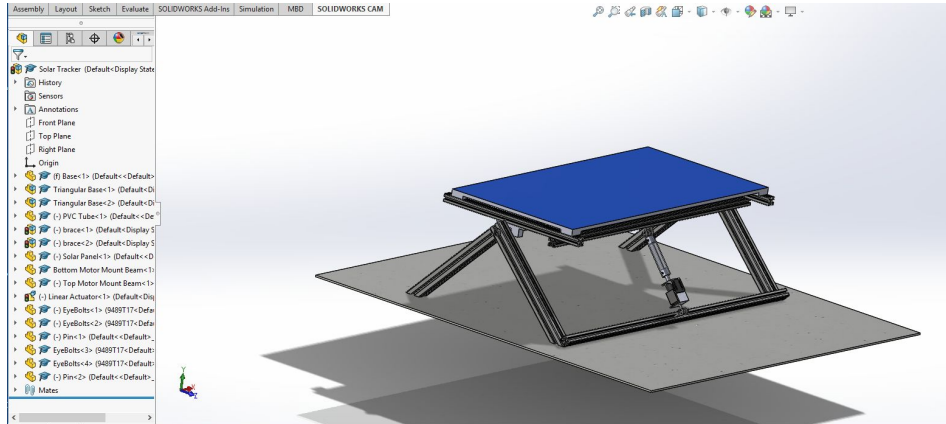
CAD Modeling

- Initial CAD
 - Motor mounted directly on axle
 - Requires constant torque
 - Solar Panels attached to aluminum t-slots via velcro



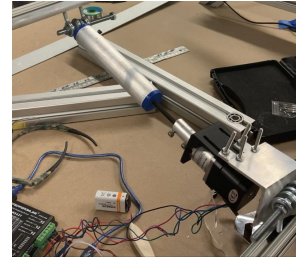
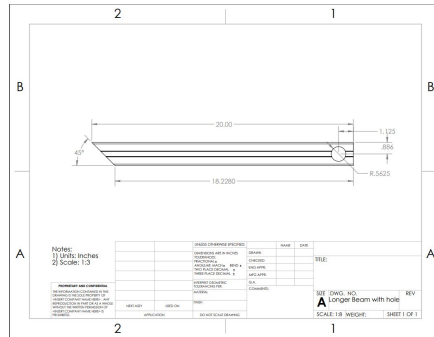
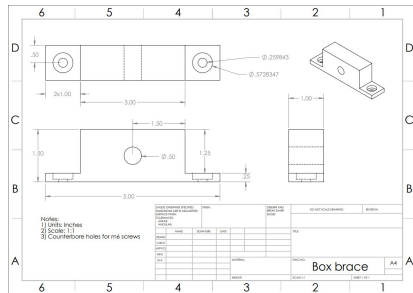
CAD Modeling

- Final CAD
 - Replaced motor with linear actuator
 - Can hold a position with no torque
 - Requires no gearing



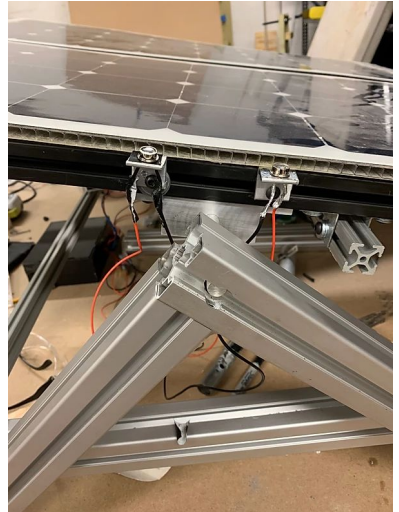
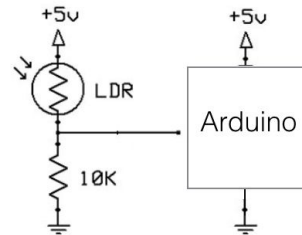
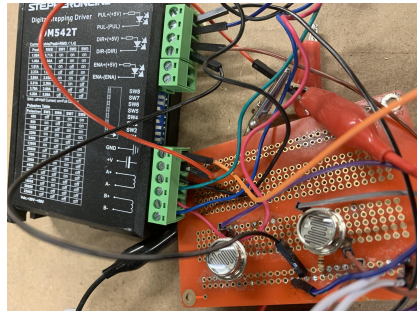
Fabrication & Manufacturing

- Frame made of Aluminum T-slots
- Linear actuator
- Machined on mill & lathe



Circuitry & Wiring

- NEMA 17 Stepper Motor & driver
 - 0.45 Nm stall torque
- Photoresistors
 - Detect varying amounts of sunlight
 - In series with a resistor to form a voltage divider



Demo

WHEN I BEGIN BLOCKING THE OTHER
PHOTORESISTOR WITH MY FINGER,
THE DIRECTION OF ROTATION
CHANGES W → C



Next Steps

- Improve tolerancing on parts
- More thorough testing before competition